Learning Interpretable, Tree-Based Projection Mappings for Nonlinear Embeddings

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Overview



- Nonlinear embeddings (NLE), such as t-SNE, are widely used DR methods.
- Recall that such DR methods do not naturally define an out-of-sample mapping, rather they directly learn a low-dimensional projection for each training point.
- We consider the problem of learning interpretable out-of-sample mappings for NLE.

Overview

Why interpreting a projection mapping matters?

- Low-dimensional embeddings may not be a faithful projection of the original, high-dimensional data:
 - The result depends in an obscure way on the objective function and on hyperparameters;
 - The resulting embeddings may give a misleading view of the data, e.g. t-SNE has a strong tendency to find clusters where none exist [1];
- Augmenting the *t*-SNE embedding with an interpretable out-of-sample mapping allows one to understand how the high-dimensional input instances are projected to the embedding and understand whether that makes sense.

What mapping should we use?



- We argue for the use of sparse oblique decision trees as an out-of-sample mapping;
- Trees are considered to be interpretable models;
- Sparse oblique trees strike a good tradeoff between accuracy and interpretability which can be controlled via a hyperparameter.
- They can make full use of any and all features of an instance.

Jointly learning an optimal tree and embedding

Consider the elastic embedding objective function:

$$E(\mathbf{Z}) = \sum_{n,m=1}^{N} \left(w_{nm} \| \mathbf{z}_n - \mathbf{z}_m \|^2 + \alpha e^{-\|\mathbf{z}_n - \mathbf{z}_m\|^2} \right)$$

Call the resulting embeddings \mathbf{z} the free embedding. If we want an out-of-sample mapping \mathbf{F} so we can project new points, then $\mathbf{z} = \mathbf{F}(\mathbf{x})$ by definition and we have a parametric embedding objective function:

$$E(\mathbf{F}) = \sum_{n,m=1}^{N} \left(w_{nm} \| \mathbf{F}(\mathbf{x}_n) - \mathbf{F}(\mathbf{x}_m) \|^2 + \alpha e^{-\|\mathbf{F}(\mathbf{x}_n) - \mathbf{F}(\mathbf{x}_m)\|^2} \right) + \lambda \phi(\mathbf{F})$$

Not easy to optimize since \mathbf{F} is non-differentiable and non-convex mapping (a tree)!

Jointly learning an optimal tree and embedding

• Solution: use the method of auxiliary coordinates (MAC) [2, 3]. Consider the following equivalent constrained problem with "auxiliary coordinates" Z:

$$\min_{\mathbf{Z},\mathbf{F}} E(\mathbf{Z}) + \lambda \,\phi(\mathbf{F}) \quad \text{s.t.} \quad \mathbf{Z} = \mathbf{F}(\mathbf{X})$$

We solve this using a penalty method. We describe the quadratic penalty method for simplicity, but in the experiments we use the augmented Lagrangian. This defines a new, unconstrained objective function:

$$\min_{\mathbf{Z},\mathbf{F}} E(\mathbf{Z}) + \lambda \,\phi(\mathbf{F}) + \mu \|\mathbf{Z} - \mathbf{F}(\mathbf{X})\|^2.$$
(1)

Finally, we optimize (1) by alternating optimization over Z and F:
Over Z, eq. (1) is the original embedding objective E but with a quadratic regularization term on Z:

$$\min_{\mathbf{Z}} E(\mathbf{Z}) + \mu \|\mathbf{Z} - \mathbf{F}(\mathbf{X})\|^2.$$

Solution: off-the-shelf algorithm to optimize the original embedding (e.g. *t*-SNE) with a minor modification to handle the additional quadratic term.

• Over **F**, eq. (1) reduces to a regression fit of a tree which we solve using the Tree Alternating Optimization (TAO) [4]:

$$\min_{\mathbf{F}} \|\mathbf{Z} - \mathbf{F}(\mathbf{X})\|^2 + \frac{\lambda}{\mu} \phi(\mathbf{F})$$

The ability of the TAO algorithm to take an initial tree and improve over it is essential here to make sure that the step over \mathbf{F} improves over the previous iteration, and to be able to use warm-start to speed up the computation.

Experiments



- Results on 20-newsgroups dataset: 6 classes, tf-idf statistics on unigrams and bigrams as features (1000 features in total).
- We used elastic embedding to produce the free embedding.
- Direct fit trains an oblique tree (using TAO) directly to a free embedding, i.e. it uses free embedding as a label.
- The first iteration ($\mu = 0$) in learning curves (left plot) represents a direct fit. Our proposed approach (tree embedding) improves over this baseline (see iterations).

Experiments



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References

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